

The *MAGMA* Package *CommMatAlg*

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Contents

1	Introduction	1
2	Mathematical background	1
3	Documentation of <i>CommMatAlg</i>	4
3.1	Creation functions	4
3.2	Algebra decompositions	4
3.3	Other functions	5
4	An example session	6

1 Introduction

The *MAGMA* ([2]) package *CommMatAlg* provides various functions on commutative matrix algebras. It was written for the study of Hecke algebras, which are prominent examples coming from the theory of modular forms (see e.g. [4] and [5]).

Before describing the functions of the package, we shall summarize the underlying theory. A good reference is [1]. In a final section, the use of the package is demonstrated in a simple example.

2 Mathematical background

We fix a field k throughout this note. By a *representation* of a k -algebra A we understand a finite dimensional k -vector space V together with a k -algebra homomorphism $\rho : A \rightarrow \text{End}_k(V)$. If

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the homomorphism is injective, the representation is said to be *faithful*. In the sequel, a subalgebra of $\text{End}_k(V)$ will be called a *matrix algebra*. Hence an abstract k -algebra is isomorphic to a matrix algebra if and only if it has a faithful representation, which is the case if and only if A is finite dimensional as a k -vector space.

One can for instance consider the (left) *regular representation*, which is defined as follows. Given an (abstract) commutative Artinian k -algebra A with k -vector space basis a_1, \dots, a_n , we let V be k^n , on which $a \in A$ acts by sending the standard basis vector $e_j = (0, \dots, 0, 1, 0, \dots, 0)$ of V to the vector $(c_{j,1}, \dots, c_{j,n})$ satisfying $aa_j = \sum_{i=1}^n c_{j,i}a_i$.

Another faithful representation is the *dual representation*. We take $V = \text{Hom}_k(A, k) = A^\vee$ and we let $(a.f)(\tilde{a}) = f(a\tilde{a})$ be the action. If we choose the same basis of A as above, the matrix representing a in the dual representation for the dual basis will be the transpose of the matrix for the regular one.

In this note we shall only be concerned with finite dimensional commutative k -algebras, which are assumed to have a 1, unless explicitly stated otherwise, in order to apply the general theory of commutative algebra. This we shall assume for the sequel.

Such a k -algebra A is *Artinian*, i.e. every descending chain of ideals becomes stationary. This is equivalent to the algebra being Noetherian and zero-dimensional. Consequently, all prime ideals are maximal, whence the Jacobson radical equals the nilradical \mathcal{N} , which is the set of all nilpotent elements in A . We number the necessarily finitely many maximal ideals of A by $\mathfrak{m}_1, \dots, \mathfrak{m}_n$. From general arguments we obtain

$$\{ \text{zero-divisors} \} = \bigcup_{i=1}^n \mathfrak{m}_i \quad \text{and} \quad \mathcal{N} = \{ \text{nilpotent el.} \} = \bigcap_{i=1}^n \mathfrak{m}_i.$$

Moreover, the primary decomposition of the zero ideal implies the existence of integers r_i such that $(0) = \mathfrak{m}_1^{r_1} \dots \mathfrak{m}_n^{r_n}$. Application of the Chinese remainder theorem yields

$$A = A/(0) = A/\mathfrak{m}_1^{r_1} \dots \mathfrak{m}_n^{r_n} \cong \prod_{i=1}^n A/\mathfrak{m}_i^{r_i} =: \prod_{i=1}^n A_i,$$

where A_i is a local Artinian quotient algebra of A . Equivalently, there exist idempotents $e_i \in A$ such that $A_i = A/(1 - e_i)A$. One also has that A_i is the localisation of A at \mathfrak{m}_i .

For every element $a \in A$ we have its *minimal polynomial* $g_a \in k[X]$. Using the theory above we find for an element $a \in A$ the following equivalences

$$a \text{ is a non-unit} \Leftrightarrow a \text{ is a zero-divisor} \Leftrightarrow g_a(0) = 0.$$

In particular, an element a , which is invertible in A , is already a unit in the algebra generated by a . We call an element $a \in A$ *diagonalisable* if the minimal polynomial g_a is a product of pairwise coprime separable irreducible polynomials and *primary* if g_a is the power of an irreducible separable polynomial. The algebra A is said to be *diagonalisable* resp. *primary* if all its elements are.

If k is perfect, we dispose of the (*additive*) *Jordan decomposition*. It asserts that any element $a \in A$ is uniquely the sum $d + n$ with $d \in A$ diagonalisable and $n \in A$ nilpotent. This result can be derived from the Jordan decomposition over a separable closure by taking Galois invariants.

Lemma 2.1 *A commutative Artinian k -algebra A is local if and only if it is primary.*

Proof. We assume first that A is primary and we let a be a non-unit of A . Hence $g_a(0) = 0$ and consequently $g_a(X) = X^r f(X)$ with $f(0) \neq 0$. As g_a is a power of an irreducible polynomial it can only be equal to X^r , whence a is nilpotent. Consequently, A is local.

Conversely, we have to show that in a local algebra A every element is primary. Since this is trivial for nilpotent elements, let $a \in A$ be a unit and \bar{a} be its image in the k -algebra A/\mathfrak{m} , which is a field extension of k . Thus the minimal polynomial $g_{\bar{a}} \in k[X]$ of \bar{a} is irreducible. Moreover we have that $g_{\bar{a}}(a)$ is in the maximal ideal and thus nilpotent. As consequently the minimal polynomial of a divides a power of $g_{\bar{a}}$, the result follows. \square

A decomposition of the k -algebra A into a product $\prod_{i=1}^n A_i$ together with a representation $\rho : A \rightarrow \text{End}_k(V)$, yields a corresponding decomposition $V = \bigoplus_{i=1}^n V_i$ by putting $V_i := \rho(e_i)V$, where the $e_i \in A$ are the natural idempotents. More precisely, we have the natural homomorphisms $A_i = A/(1 - e_i)A \rightarrow \text{End}(V_i)$, $a \mapsto \rho(a)|_{V_i}$, which provide a factorisation of ρ :

$$\rho : A \cong \prod_{i=1}^n A_i \rightarrow \prod_{i=1}^n \text{End}(V_i) \hookrightarrow \text{End}(V).$$

In other words, after a suitable choice of basis all matrices will be zero except for blocks on the diagonal corresponding to $A_i \rightarrow \text{End}(V_i)$.

Such a decomposition of V can for instance be calculated by considering for each maximal ideal \mathfrak{m} the sequence

$$V[\mathfrak{m}] \subset V[\mathfrak{m}^2] \subset \dots \subset V[\mathfrak{m}^r],$$

where $V[\mathfrak{m}^i]$ is defined to be the subvector space of those $v \in V$ satisfying $\rho(m)v = 0$ for all $m \in \mathfrak{m}^i$. By looking at the natural idempotent $e_i \in A$ corresponding to the maximal ideal $\mathfrak{m} = \mathfrak{m}_i$, one immediately sees that $V_i = \rho(e_i)V$ equals $V[\mathfrak{m}_i^r]$, where r can be chosen as the minimal integer such that the sequence of inclusions above becomes stationary. Explicitly, one has $V_i = \bigcap \text{Ker}(\rho(g))$, where g runs through a set of ideal generators of \mathfrak{m}_i^r .

If one chooses a basis of $V[\mathfrak{m}]$, extends it to a basis of $V[\mathfrak{m}^2]$ and so on, one finds that the blocks of the matrices corresponding to \mathfrak{m} are (lower) triangular, provided that $k = A/\mathfrak{m}$ and that k is perfect.

We also note that $V[\mathfrak{m}]$ is the biggest subspace of $V[\mathfrak{m}^r]$, on which A acts diagonalisably, i.e. if $\bar{\rho} : A \rightarrow \text{End}_k(V[\mathfrak{m}])$ denotes the restriction, then $g_{\bar{\rho}(a)}$ is irreducible for all $a \in A$. We shall call $V[\mathfrak{m}]$ the *generalised eigenspace* corresponding to the maximal ideal \mathfrak{m} .

A local commutative k -algebra A is said to be *Gorenstein* if the annihilator \mathfrak{a} of the maximal ideal is a simple A -module. This is the case if and only if \mathfrak{a} is a 1-dimensional A/\mathfrak{m} -vector space. Accordingly, we define the *Gorenstein defect* of the local algebra to be this dimension minus 1. A commutative algebra is called *Gorenstein* if all its localisations are. Hence we define its *Gorenstein defect* to be the supremum of the Gorenstein defects of the localisations.

The algorithms implemented are easy consequences of the theory outlined above.

3 Documentation of *CommMatAlg*

If `PATH` is the directory in which `CommMatAlg.mg` is stored, type

```
Attach ("PATH/CommMatAlg.mg");
```

in order to use the package. We remark that vectors in *MAGMA* are *row vectors*. This convention is adopted below.

3.1 Creation functions

- `intrinsic MatrixAlgebra (L :: SeqEnum) -> AlgMat`
- `intrinsic MatrixAlgebra (L :: SeqEnum, S :: Tup) -> AlgMat`
- `intrinsic MatrixAlgebra (A :: AlgMat, S :: Tup) -> AlgMat`

Creates the matrix algebra generated by the given data:

- the (commuting) matrices in the list `L`.
 - the restrictions to the stable subspace `S` (see section on algebra decompositions) of the (commuting) matrices in the list `L`.
 - the restriction to the stable subspace `S` of the matrix algebra `A`.
- `intrinsic Transpose (A :: AlgMat) -> AlgMat`

Given a matrix algebra `A`, this function creates the transposed matrix algebra.

3.2 Algebra decompositions

Let us assume that we have a matrix algebra A of degree d , i.e. $A < \text{End}(k^d)$. A *decomposition* $\prod_{i=1}^n A_i$ of A corresponds to a direct sum $k^d = \bigoplus_{i=1}^n V_i$, where each k -vector space V_i is stabilised by A .

Such a decomposition is represented gives rise to a tuple T, S as follows. S is a tuple $\langle C, D \rangle$, where $D = C^{-1}$ and C is the base change matrix from the standard basis to a basis $\{v_{1,1}, \dots, v_{1,n_1}, v_{2,1}, \dots, v_{2,n_2}, \dots, v_{n,1}, \dots, v_{n,n_n}\}$ of V s.t. $\{v_{i,1}, \dots, v_{i,n_i}\}$ is a basis of V_i . T is an n -tuple $\langle \langle C_1, D_1 \rangle, \dots, \langle C_n, D_n \rangle \rangle$ with C_i resp. D_i corresponding to the rows of C resp. the columns of C^{-1} belonging to the i -th subspace V_i . In other words, given an element of A considered as a matrix M w.r.t. to the standard basis of V , then $C_i M D_i$ is the block of M corresponding to the restriction of M to V_i . V_i resp. $\langle C_i, D_i \rangle$ are both called *stable subspaces*.

Moreover, $C_i D_i$ is the identity matrix of size the dimension of V_i and $D_i C_i$ is the idempotent in $\text{End}(V)$ corresponding to V_i in the given decomposition, i.e. V_i is the image of the idempotent $D_i C_i$.

We allow also that $\bigoplus_{i=1}^n V_i$ is a proper subspace of k^d . Those may occur in the program for instance as common eigenspaces. Internally, some complement is used in order to make the computations work.

- `intrinsic Idempotents (D :: Tup) -> SeqEnum, Tup`

Given a tuple of stable subspaces $D = \langle \langle C_1, D_1 \rangle, \dots, \langle C_n, D_n \rangle \rangle$, this function returns a list of the idempotents corresponding to the subspaces and a tuple $\langle C, C^{-1} \rangle$, where C is the base change matrix from the standard basis to a basis for the sum of the stable subspaces (plus some complement, if necessary).

- `intrinsic CommonLowerTriangular (A :: AlgMat) -> Tup, Tup`
`intrinsic LocalDecomposition (A :: AlgMat) -> Tup, Tup`

Given a matrix algebra A of degree d , which decomposes into n local factors $\prod_{i=1}^n A_i$, these two identical functions decompose k^d into $\bigoplus_{i=1}^n V_i$ such that A stabilizes each V_i and such that $A_i < \text{End}(V_i)$. More precisely, the decomposition is obtained by for each maximal ideal \mathfrak{m}_i taking a basis of $k^d[\mathfrak{m}_i]$, extending it to a basis of $k^d[\mathfrak{m}_i^2]$ and so on. If the algebra is defined over the field A/\mathfrak{m}_i , one obtains by this a basis with respect to which the blocks of the matrices corresponding to \mathfrak{m}_i are lower triangular.

- `intrinsic CommonGeneralizedEigenspaces (A :: AlgMat) -> Tup`

Given a matrix algebra A of degree d , which decomposes into n local factors $\prod_{i=1}^n A_i$, this function computes the subspace $\bigoplus_{i=1}^n k^d[\mathfrak{m}_i]$ of k^d . The vector space $k^d[\mathfrak{m}_i]$ is called a *generalised eigenspace*. If A is defined over A/\mathfrak{m}_i , then $k^d[\mathfrak{m}_i]$ is the simultaneous eigenspace corresponding to \mathfrak{m}_i .

- `intrinsic CommonEigenspaces (A :: AlgMat) -> Tup`

Given a matrix algebra A of degree d , this function computes the direct sum of all simultaneous eigenspaces.

- `intrinsic Eigenspaces (M :: Mtrx) -> Tup`

This function is the same as `CommonEigenspaces` for the algebra generated by the matrix M .

- `intrinsic RestrictMatrix (M :: Mtrx, P :: Tup) -> Mtrx`

Given a tuple $P = \langle C, D \rangle$, calculates the matrix CMD . For instance, P could correspond to a stable subspace.

- `intrinsic RestrictList (L :: SeqEnum, P :: Tup) -> SeqEnum`

Applies the function `RestrictMatrix` to all matrices in the list L .

3.3 Other functions

- `intrinsic JordanDecomposition (M :: Mtrx) -> Mtrx, Mtrx`

Calculates the decomposition $M = D + N$ with D diagonalisable and N nilpotent.

- `intrinsic GorensteinDefect (A :: AlgMat) -> RngIntElt`
Returns the Gorenstein defect of the commutative matrix algebra A.
- `intrinsic IsGorenstein (A :: AlgMat) -> BoolElt`
Returns whether the commutative matrix algebra A is Gorenstein, that is has Gorenstein defect 0.
- `intrinsic IsLocalAlgebra (A :: AlgMat) -> BoolElt`
Returns whether the algebra A is local.
- `intrinsic CommonResidueField (A :: AlgMat) -> Any`
Returns the field generated by the residue fields of the matrix algebra A.
- `intrinsic ChangeRingList (L :: SeqEnum , F :: Rng) -> SeqEnum`
Changes the coefficient ring of all the matrices in the list L to the ring F.
- `intrinsic IdealTorsion (m :: AlgMat) -> ModTupFld`
Given an ideal m in a matrix algebra of degree d over a field F , calculate the sub vector space of F^d consisting of those elements killed by every element of m.
- `intrinsic UPO (A :: AlgMat) -> RngIntElt`
Computes the unipotency order of the matrix algebra A. That is by (my personal) definition the number $\max_{\mathfrak{m} \triangleleft A \text{ maximal}} \left(\min_{n \geq 0} (\mathfrak{m}^n = (0)) \right)$.

4 An example session

We assume that the package is stored in the folder PATH. First we attach the package:

```
> Attach("PATH/CommMatAlg.mg");
```

We create the full matrix algebra of 4 by 4 matrices over $\text{GF}(2)$.

```
> alg := MatrixAlgebra (GF(2), 4);
```

Next, we create the following three matrices:

```
> id := alg!1; id;
[1 0 0 0]
[0 1 0 0]
[0 0 1 0]
[0 0 0 1]
> x := alg![1,1,1,1,0,0,0,0,1,1,0,1,0,0,1,0]; x;
[1 1 1 1]
[0 0 0 0]
```

```

[1 1 0 1]
[0 0 1 0]
> y := alg![1,0,1,1,0,0,0,0,1,1,0,1,0,1,1,0]; y;
[1 0 1 1]
[0 0 0 0]
[1 1 0 1]
[0 1 1 0]

```

Now we take the matrix algebra generated by these matrices:

```

> A := MatrixAlgebra([id,x,y]); A;
Matrix Algebra of degree 4 with 3 generators over GF(2)

```

Let us check whether the algebra is commutative.

```

> Centre(A) eq A;
true

```

Its dimension is:

```

> Dimension(A);
4

```

Now we generate its local factors.

```

> L,S := LocalDecomposition(A); #L;
2

```

There are two of them. The first one is just a copy of \mathbb{F}_2 :

```

> A1 := MatrixAlgebra(A,L[1]); A1;
Matrix Algebra of degree 1 with 3 generators over GF(2)

```

The second is more interesting.

```

> A2 := MatrixAlgebra(A,L[2]); A2;
Matrix Algebra of degree 3 with 3 generators over GF(2)
> Basis(A2);
[
  [1 0 0]
  [0 1 0]
  [0 0 1],

  [0 0 0]
  [0 0 0]
  [1 0 0],

  [0 0 0]
  [0 0 0]
  [0 1 0]
]

```

We see that the algebra consists of lower triangular matrices, as it ought to, since the residue field is the ground field and the algebra was generated by choosing such a basis.

We can also base change the whole algebra to the lower triangular basis:

```
> B := MatrixAlgebra(A, S); Basis(B);  
[  
  [1 0 0 0]  
  [0 0 0 0]  
  [0 0 0 0]  
  [0 0 0 0],  
  
  [0 0 0 0]  
  [0 1 0 0]  
  [0 0 1 0]  
  [0 0 0 1],  
  
  [0 0 0 0]  
  [0 0 0 0]  
  [0 0 0 0]  
  [0 1 0 0],  
  
  [0 0 0 0]  
  [0 0 0 0]  
  [0 0 0 0]  
  [0 0 1 0]  
  ]
```

References

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